GROUP MEMBERS

Academic Staffs



Signal Processing Biomedical Eng. **Intelligent Control**



Control System **Process Control** System Modeling

Prof. Ir. Dr. Siti Anom

Assoc. Prof. Dr. Samsul Bahari



Intelligent Control Computer Vision Robotics



Automotive Electronic Control **Intelligent Control Energy Management** System **Energy Storage**

Prof. Dr. Mohammad Hamiruce

Assoc. Prof. Ir. Dr. Mohd Khair



Control System Biomedical Eng. Noise/Vibration Control



Control System Intelligent Control System Modeling

Assoc. Prof. Ir. Dr. Raja

Assoc. Prof. Ts. Dr. Azura



Intelligent Control Biomedical Eng. Twin Digital-Modeling Pattern Recognition



Control System System Modeling Artificial Intelligence Fault Detection & Diagnosis

Assoc. Prof. Ts. Dr. Asnor

Dr. Ribhan Zafira



Biomedical Eng. **Image Processing** Robotics



Control System Nonlinear Control Robotics **Artificial Intelligence**

Ir. Ts. Dr. Hafiz Rashidi

Ts. Dr. Nor Mohd Haziq





Confided us



eng.ossp@upm.edu.my



Control System & Stand Processing Research Centre UPM









KEJURUTERAAN فاكولتي كجوروتراءن

Teaching . Research . Services

Technical Staffs















CSSP group is one of the three main research groups at the Department of Electrical & Electronic Engineering, Faculty of Engineering, Universiti Putra Malaysia (UPM), located in UPM Serdang. Established in 1996. CSSP has consistently showcased its leadership, solidifying its position as one of the leading research centres for control engineering in Malaysia.

VISION

To be leading expert in the fundamentals of control theory & its application in the industry to enhance quality of life for the local & international communities.

MISSION

- 1. To **contribute** to knowledge in control engineering & related fields through systematic & comprehensive research.
- 2. To educate the community on control engineering applications & principles to enhance productivity & improve quality.

UNDERGRADUATE SUBJECT TAUGHT

- 1. Control Systems
- 2.Instrumentation & Measurement
- 3.Embedded Control System
- 4. Multivariable Control System
- 5. Signal Processing
- 6. Industrial Control Electronics
- 7. Intelligent Control System
- 8. Modeling & Simulation
- 9. Industrial Process Control
- 10.Control System Design

POSTGRADUATE PROGRAM

- 1. Doctor of Philosophy
- 2. Master of Science (By Research)
- 3. Master in Control System Engineering (By Taught Course)













1. LAB VIEW & MATLAB Systems

4. Embedded System Development Board

- 5. Rigs for Algorithm Testing (servo, pendulum, twin rotor helicopter, robot arm)
- 6. Battery Testing & Monitoring
- 7. Battery Management System
- 8. Bird Slaughtering System
- 9.3D Printer

TRAINING

- 1.LABVIEW Software & Hardware
- 2. MATLAB Simulink Integration
- 3.V -Shape Engineering Application
- 4. System Modeling & Simulation
- 5. Fault Detection & Diagnosis
- 6. Signal & Image Processing
- 7.3D Printing
- 8. SolidWorks Software



RM 18.332,000 RESEARCH INCOME

96 Ph.D. & 168 MSc.

STUDENT GRADUATED

CSSP RESEARCH FOCUS

3. Modeling & Optimization

5. Artificial Intelligence

8. Robotics & Vision

6. Fault Detection System

7. Engine Management System

RECENT ACHIEVEMENTS

1. Linear & Nonlinear Control Systems

17 patents & 4 IPR INNOVATION

124 (8773 Citations) GROUP'S H-INDEX (SCOPUS

> 20 projects

RECORDED PROJECT

78 Ph.D. & 10 MSc.

CURRENT STUDENT

25 countries & 62 affiliations COLLABORATORS

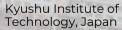
> 504 iournals & 553 conferences

COLLABORATIONS

UK-based Universities (Imperial, Surrey, Sheffield & Southampton)

Korea Advanced Institute of Science & Technology, South Korea





- 1.SIRIM Berhad
- 2. Malaysia Space Agency (MYSA)
- 3. Malaysia Nuclear Agency
- 4. PETRONAS
- 5. Local & International Automotive Company
- 6. National Instruments (NI)
- 7. Malaysian Research Institute on Ageing (MyAgeing)
- 8. Tenaga Nasional Berhad

1. Symposium on Control System & Signal Processing

- 2. Seminar on Postgraduate Research in CSSP
- 3. CSSP Students & Lecturers Gathering
- 4. MATLAB Workshop
- 5. Industrial Visit
- 6. Visiting Professor Program
- 7. Seminar on Control of Hybrid Dynamic Systems









